Combinatorial Designs Man versus Machine

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# The theory of combinatrial designs

• 1850 • Thomas Kirkman

## Statistical experiments

Balanced incomplete block designs

#### Fiber-optic communication

Optical orthogonal codes

#### Software testing

Covering arrays

## Schoolgirls problem

#### Electrical engineering

 Generalized balanced tournament designs



#### Interconnection computer networks

Cyclic projective planes



## Cryptographic communication

Orthogonal arrays

#### Theory of error-correcting codes

Steiner systems

## Agricultural engineering

- Latin squares
- Algebra
   Number theory

Geometry

## Binary Golay code

• (24, 12, 8) error-correcting code

#### Application

- NASA deep space missions
- Radio communications



Binary Golay code can be constructed from Steiner system 5-(24, 8, 1).

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Figure: Steiner system 2-(7, 3, 1)









Figure: Steiner system 2-(7,3,1)

## Definition

A Steiner system 2-(v, 3, 1) is a finite incidence structure  $(\mathcal{V}, \mathcal{B})$ , where

- $\mathcal{V}$  is a set of v elements called *points*,
- ▶ B is a set of 3-subsets of V called *blocks*,
- every set of 2 points is contained in precisely 1 block.

# The existence of Steiner triple systems









Figure: Dave vs. HAL in 2001: A Space Odyssey

• Designs  $(\mathcal{V}, \mathcal{B})$  and  $(\mathcal{V}, \mathcal{B}')$  are isomorphic if there exists a bijection  $\alpha : \mathcal{V} \to \mathcal{V}$  such that  $\alpha \mathcal{B} = \mathcal{B}'$ .



# Steiner triple systems - automorphisms

- Automorphism of  $(\mathcal{V}, \mathcal{B})$  is a permutation  $\pi : \mathcal{V} \to \mathcal{V}$  such that  $\pi(\mathcal{B}) = \mathcal{B}$ .
- Set of all automorphisms of a design  $(\mathcal{V}, \mathcal{B})$  is a group.



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# Steiner triple systems - generalization



## Definition

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# Steiner triple systems - generalization



## Definition

A Steiner system 2-(v, k, 1) is a finite incidence structure  $(\mathcal{V}, \mathcal{B})$ , where

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- B is a set of k-subsets of V called blocks,
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# Steiner triple systems - generalization



## Definition

A Steiner system t-(v, k, 1) is a finite incidence structure  $(\mathcal{V}, \mathcal{B})$ , where

- $\mathcal{V}$  is a set of v elements called *points*,
- B is a set of k-subsets of V called blocks,
- every set of t points is contained in precisely 1 block.

# New directions - Steiner systems in vector spaces



## Definition

A Steiner system t- $(v, k, 1)_q$  is a finite incidence structure  $(\mathcal{V}, \mathcal{B})$ , where

- $\mathcal{V}$  is a vector space of dimension v over finite field  $\mathbb{F}_q$ ,
- $\mathcal{B}$  is a set of *k*-dimensional subspaces of  $\mathcal{V}$  called *blocks*,
- every *t*-dimensional subspace of  $\mathcal{V}$  is contained in precisely 1 block.

Peter Cameron's Blog (2014)

# I think that this is the most important area to attack next.

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#### Examples.

- ▶  $1-(v,k,1)_q$  designs
- ▶ 2-(13, 3, 1)<sub>2</sub> designs
- ▶ ???
- M. Braun, T. Etzion, P. Ostergard, A. Vardy, A. Wassermann Existence of q-analogs of Steiner systems. arXiv:1304.1462 (2013).

Open problem: the existence of  $2-(7,3,1)_q$ 



Question: does  $2-(7,3,1)_q$  exist?

## Theorem (Braun, Kiermaier, Nakić, 2015)

If a 2- $(7,3,1)_2$  designs exists, it is either rigid or its automorphism group is cyclic of order 2, 3 or 4.

 M. Braun, M. Kiermaier, A. Nakić. On the automorphism group of a binary q-analog of the Fano plane. European Journal of Combinatorics, to appear (2015).

# Combinatorial designs - existence and enumeration



## Definition

A Steiner system t-(v, k, 1) is a finite incidence structure  $(\mathcal{V}, \mathcal{B})$ , where

- $\mathcal{V}$  is a set of v elements called *points*,
- B is a set of k-subsets of V called blocks,
- every set of t points is contained in precisely 1 block.

# Combinatorial designs - existence and enumeration



## Definition

A t- $(v, k, \lambda)$  design is a finite incidence structure  $(\mathcal{V}, \mathcal{B})$ , where

- $\mathcal{V}$  is a set of v elements called *points*,
- B is a set of k-subsets of V called blocks,
- every set of t points is contained in precisely  $\lambda$  blocks.

# The existence of 2- $(v, k, \lambda)$ designs

Necessary conditions (integrality)

$$\lambda \frac{v-1}{k-1}$$
 is integer 
$$\lambda \frac{v(v-1)}{k(k-1)} \text{ is integer}$$



Figure: Gary Kasparov vs. Deep Blue

# Theorem (Wilson, 1975)

For every fixed k and  $\lambda$ , there is a constant  $C(k, \lambda)$ , so that if  $v > C(k, \lambda)$  and integrality conditions are satisfied, there exists a 2- $(v, k, \lambda)$  design.

- R. Wilson. An existence theory for pairwise balanced designs, III: Proof of the existence conjectures. J. Comb. Theory A 18(1), 71–79 (1975).
- ▶ P. Keevash. The existence of designs. arXiv:1401.3665 (2014).

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$t - (v, k, \lambda)$	No.	$t-(v,k,\lambda)$	No.
2 - (7, 3, 1)	1	3 - (8, 4, 1)	1
2 - (7, 3, 2)	4	3 - (10, 4, 1)	1
2 - (7, 3, 3)	10	3 - (14, 4, 1)	4
2 - (7, 3, 9)	17785	3 - (16, 7, 5)	?
2 - (8, 3, 6)	3077244	3 - (17, 7, 7)	?
2 - (8, 4, 3)	4	3 - (19, 9, 140)	?
2 - (8, 4, 12)	> 2310	3 - (19, 9, 644)	?
2 - (15, 5, 2)	0	3 - (20, 5, 8)	> 1
2 - (39, 13, 6)	?	4 - (17, 5, 1)	?
2 - (40, 10, 3)	?	4-(23,7,1)	> 1
2 - (57, 15, 10)	?	4 - (32, 5, 5)	> 1
2 - (55, 10, 4)	?	5 - (12, 6, 1)	> 1
2 - (133, 7, 1)	?	5 - (18, 6, 1)	?
2 - (175, 30, 6)	?	5 - (30, 12, 220)	> 1
2 - (211, 7, 1)	?	5 - (60, 18, 3060)	> 1
2 - (400, 20, 1)	?	6 - (19, 7, 1)	?
2 - (421, 21, 1)	?	7 - (33, 8, 10)	> 1

Handbook of Combinatorial Designs, eds. C. Colbourn, J. Dinitz, 2007.

► Designs  $(\mathcal{V}, \mathcal{B})$  and  $(\mathcal{V}', \mathcal{B}')$  are isomorphic if there exists a bijection  $\alpha : \mathcal{V} \to \mathcal{V}'$ such that  $\alpha \mathcal{B} = \mathcal{B}'$ .

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Computational construction of designs

# Computational methods for construction of designs

## Exhaustive search

▶ The incidence matrix of  $(\mathcal{V}, \mathcal{B})$ 



I	- 0	1	1	1	0	0	ך 0
	1	1	0	0	1	0	0
	1	0	1	0	0	1	0
	1	0	0	1	0	0	1
	0	1	0	0	0	1	1
	0	0	1	0	1	0	1
	0	0	0	1	1	1	0 ]

Design	Number of matrices	
2 - (7, 3, 1)	$2^{7 \cdot 7}$	$\approx 10^{16}$
2 - (15, 3, 1)	$2^{15\cdot 35}$	$\approx 10^{175}$
3 - (16, 7, 5)	$2^{16 \cdot 80}$	$\approx 10^{426}$
2 - (175, 30, 6)	$2^{175 \cdot 210}$	$pprox 10^{12250}$

## Nonexhaustive search

- Automorphism of a design  $(\mathcal{V}, \mathcal{B})$  is a mapping  $\pi : \mathcal{V} \to \mathcal{V}$  such that  $\pi(\mathcal{B}) = \mathcal{B}$ .
- ▶ Set of all automorphisms of a design  $(\mathcal{V}, \mathcal{B})$  is a group.



Construction of designs with prescribed automorphism group:

The Kramer-Mesner method
 E.S. Kramer, D.M. Mesner.
 t-designs on hypergraphs.
 Discret. Math. 15, 263–296 (1976).
 The method of tactical decomposition
 Z. Janko, T. van Trung.

Construction of a new symmetric block design for (78, 22, 6) with the help of tactical decompositions.

J. Comb. Theory A 40, 451-455 (1985).

# Theorem (Nakić, 2015)

If a 3-(16,7,5) design exists, then it is either rigid or its full automorphism group is a 2-group.



Figure: Jeopardy! Pros vs. Watson

## Z. Eslami.

On the possible automorphisms of a 3-(16, 7, 5) design. Ars Combinatoria 95, 217-224 (2010).

#### A. Nakić.

Non-existence of a simple 3-(16, 7, 5) design with an automorphism of order 3. Discrete Mathematics 338(4), 555-565 (2015).

Example: Tactical decomposition of 2-(8, 4, 3) design



N	Incid	lanca	matrix	
	incia	lence	matrix	ŝ

	$B_1$	$B_2$	$B_3$	$B_4$	$B_5$	$B_6$	$B_7$	$B_8$	$B_9$	$B_{10}$	$B_{11}$	$B_{12}$	$B_{13}$	$B_{14}$
$\overline{p_1}$	1	0	1	0	0	1	1	0	0	0	1	1	0	1
$p_2$	0	1	1	0	1	0	0	0	1	0	1	0	1	1
$p_3$	1	0	0	1	1	0	0	1	0	0	1	1	1	0
$p_4$	0	1	0	1	0	1	0	0	0	1	0	1	1	1
$p_5$	1	0	1	0	0	1	0	1	1	1	0	0	1	0
$p_6$	0	1	1	0	1	0	1	1	0	1	0	1	0	0
$p_7$	1	0	0	1	1	0	1	0	1	1	0	0	0	1
$p_8$	0	1	0	1	0	1	1	1	1	0	1	0	0	0

Example: Tactical decomposition of 2-(8, 4, 3) design



N	Incid	lonco	matrix
	incia	lence	matrix

	$B_1$	$B_2$	$B_3$	$B_4$	$B_5$	$B_6$	$B_7$	$B_8$	$B_9$	$B_{10}$	$ B_{11} $	$B_{12}$	$B_{13}$	$B_{14}$
$\overline{p_1}$	1	0	1	0	0	1	1	0	0	0	1	1	0	1
$p_2$	0	1	1	0	1	0	0	0	1	0	1	0	1	1
$p_3$	1	0	0	1	1	0	0	1	0	0	1	1	1	0
$p_4$	0	1	0	1	0	1	0	0	0	1	0	1	1	1
$p_5$	1	0	1	0	0	1	0	1	1	1	0	0	1	0
$p_6$	0	1	1	0	1	0	1	1	0	1	0	1	0	0
$p_7$	1	0	0	1	1	0	1	0	1	1	0	0	0	1
$p_8$	0	1	0	1	0	1	1	1	1	0	1	0	0	0
			$[\rho_{ij}]$	$=  _{1}$	2	3 1		$\kappa_i$	$j = \lfloor$	2 2	3 1			

$$= \begin{bmatrix} 1 & 2 & 1 & 3 \\ 1 & 2 & 3 & 1 \end{bmatrix} \qquad [\kappa_{ij}] = \begin{bmatrix} 2 & 2 & 1 & 3 \\ 2 & 2 & 3 & 1 \end{bmatrix}$$

# Definition

A tactical decomposition of a design  $(\mathcal{V},\mathcal{B})$  is any partition

 $\mathcal{V} = \mathcal{V}_1 \sqcup \cdots \sqcup \mathcal{V}_m, \ \mathcal{B} = \mathcal{B}_1 \sqcup \cdots \sqcup \mathcal{B}_n$ 

with the property that there exist nonnegative integers  $ho_{ij}$  and  $\kappa_{ij}$  such that

- each point of  $\mathcal{V}_i$  lies in precisely  $\rho_{ij}$  blocks of  $\mathcal{B}_j$ ,
- and each block of  $\mathcal{B}_j$  contains precisely  $\kappa_{ij}$  points from  $\mathcal{V}_i$ .

Matrices  $\mathcal{R} = [\rho_{ij}]$  and  $\mathcal{K} = [\kappa_{ij}]$  are called *tactical decomposition matrices*.

Orbits of  $\mathcal{V}$  and orbits of  $\mathcal{B}$  under an action of G form a tactical decomposition of  $(\mathcal{V}, \mathcal{B})$ .



The method of tactical decomposition for 2-designs

$$[\rho_{ij}] = \begin{bmatrix} 1 & 2 & 1 & 3 \\ 1 & 2 & 3 & 1 \end{bmatrix} \qquad [\kappa_{ij}] = \begin{bmatrix} 2 & 2 & 1 & 3 \\ 2 & 2 & 3 & 1 \end{bmatrix}$$

Γ1	0	1	0	0	1	1	0	0	0	1	1	0	1٦
0	1	1	0	1	0	0	0	1	0	1	0	1	1
1	0	0	1	1	0	0	1	0	0	1	1	1	0
0	1	0	1	0	1	0	0	0	1	0	1	1	1
1	0	1	0	0	1	0	1	1	1	0	0	1	0
0	1	1	0	1	0	1	1	0	1	0	1	0	0
1	0	0	1	1	0	1	0	1	1	0	0	0	1
0	1	0	1	0	1	1	1	1	0	1	0	0	0

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 $(\mathcal{V},\mathcal{B})$  is a 2- $(v,k,\lambda_2)$  design with tactical decomposition

$$\mathcal{V}=\mathcal{V}_1\sqcup\cdots\sqcup\mathcal{V}_m,$$

$$\mathcal{B}=\mathcal{B}_1\sqcup\cdots\sqcup\mathcal{B}_n.$$



Figure: Terminator

$$\sum_{j=1}^{n} \rho_{lj} \kappa_{rj} = \begin{cases} \lambda_1 + (|\mathcal{V}_r| - 1) \cdot \lambda_2, & l = r, \\ |\mathcal{V}_r| \cdot \lambda_2, & l \neq r. \end{cases}$$

$$[\rho_{ij}] = \begin{bmatrix} \vdots & \vdots \\ \rho_{l1} & \cdots & \rho_{ln} \\ \vdots & \vdots \\ \vdots & & \vdots \\ \vdots & & \vdots \end{bmatrix} \qquad [\kappa_{ij}] = \begin{bmatrix} \vdots & \vdots \\ \vdots & \vdots \\ \kappa_{r1} & \cdots & \kappa_{rn} \\ \vdots & \vdots \end{bmatrix}$$

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$$\sum_{j=1}^{14} \rho_{lj} \kappa_{rj} = \begin{cases} 7 + (4-1) \cdot 3, & l = r, \\ 4 \cdot 3, & l \neq r. \end{cases}$$

## 

$$[\rho_{ij}] = \begin{bmatrix} 1 & 2 & 1 & 3 \\ 1 & 2 & 3 & 1 \end{bmatrix} \qquad [\kappa_{ij}] = \begin{bmatrix} 2 & 2 & 1 & 3 \\ 2 & 2 & 3 & 1 \end{bmatrix}$$

Theorem (Krčadinac, Nakić, Pavčević, 2014) Let  $\mathcal{D} = (\mathcal{V}, \mathcal{B})$  be a t- $(v, k, \lambda_t)$  design with tactical decomposition

 $\mathcal{V} = \mathcal{V}_1 \sqcup \cdots \sqcup \mathcal{V}_m, \ \mathcal{B} = \mathcal{B}_1 \sqcup \cdots \sqcup \mathcal{B}_n.$ 

Then the coefficients of  $\mathcal{R} = [\rho_{ij}]$  and  $\mathcal{K} = [\kappa_{ij}]$  satisfy

$$\sum_{j=1}^{m} \rho_{i_{1j}} \kappa_{i_{1j}}^{m_{1}-1} \kappa_{i_{2j}}^{m_{2}} \cdots \kappa_{i_{s}j}^{m_{s}} = \sum_{\omega_{1}=1}^{m_{1}} \sum_{\omega_{2}=1}^{m_{2}} \cdots \sum_{\omega_{s}=1}^{m_{s}} \lambda_{\omega_{1}+\dots+\omega_{s}} {m_{1} \atop \omega_{1}} (|\mathcal{V}_{i_{1}}|-1)_{\omega_{1}-1} \prod_{j=2}^{s} {m_{j} \atop \omega_{j}} (|\mathcal{V}_{i_{j}}|)_{\omega_{j}}.$$

 V. Krčadinac, A. Nakić, M. O. Pavčević. Equations for coefficients of tactical decomposition matrices for t-designs. Des. Codes Cryptogr. 72(2), 465–469 (2014).

## Theorem (Krčadinac, Nakić, Pavčević, 2011)

$$\sum_{j=1}^{n} \rho_{lj} \kappa_{rj} = \begin{cases} \lambda_1 + (|\mathcal{V}_r| - 1) \cdot \lambda_2, & l = r, \\ |\mathcal{V}_r| \cdot \lambda_2, & l \neq r. \end{cases}$$

$$\begin{split} \sum_{j=1}^{n} \rho_{lj} \kappa_{rj} \kappa_{sj} &= \\ &= \begin{cases} \lambda_1 + 3\left(|\mathcal{V}_l| - 1\right) \cdot \lambda_2 + \left(|\mathcal{V}_l| - 1\right) \cdot \left(|\mathcal{V}_l| - 2\right) \cdot \lambda_3, & \text{for } l = r = s, \\ |\mathcal{V}_r| \cdot |\mathcal{V}_s| \cdot \lambda_3, & \text{for } l \neq r \neq s \neq l, \\ |\mathcal{V}_s| \cdot \lambda_2 + \left(|\mathcal{V}_r| - 1\right) \cdot |\mathcal{V}_s| \cdot \lambda_3, & \text{otherwise.} \end{cases} \end{split}$$

## Theorem (Nakić, 2015)

If a 3-(16,7,5) design exists, then it is either rigid or its full automorphism group is a 2-group.

# New directions - designs in vector spaces



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## Definition

A t- $(v, k, \lambda)$  design is a finite incidence structure  $(\mathcal{V}, \mathcal{B})$ , where

- $\mathcal{V}$  is a set of v elements called *points*,
- ▶ B is a set of k-subsets of V called blocks,
- every set of t points is contained in precisely  $\lambda$  blocks.

# New directions - designs in vector spaces



## Definition

A t- $(v, k, \lambda_t)$  design over a finite field is a pair  $(\mathcal{V}, \mathcal{B})$ , where

- $\mathcal{V}$  is a *v*-dimensional vector space over the finite field  $\mathbb{F}_q$
- ▶ B is a set of k-dimensional subspaces of V called blocks,
- every *t*-dimensional subspace of  $\mathcal{V}$  is contained in precisely  $\lambda$  blocks.
- P. Cameron. Locally symmetric designs. Geom. Dedicata 3, 56–76, (1974).
- P. Delsarte. Association schemes and t-designs in regular semilattices. J. Combin. Theory Ser. A 20(2), 230–243 (1976).

Theorem (Nakić, Pavčević, 2014) If  $(\mathcal{V}, \mathcal{B})$  is a 2- $(v, k, \lambda)_q$  design with tactical decomposition

$$\mathcal{V} = \mathcal{V}_1 \sqcup \cdots \sqcup \mathcal{V}_m, \ \mathcal{B} = \mathcal{B}_1 \sqcup \cdots \sqcup_n,$$

then

$$\sum_{j=1}^{n} \rho_{lj} \kappa_{rj} = \begin{cases} \lambda_1 + (|\mathcal{V}_r| - 1) \cdot \lambda_2, & l = r, \\ |\mathcal{V}_r| \cdot \lambda_2, & l \neq r. \end{cases}$$

A. Nakić, M.O. Pavčević. *Tactical* decompositions of designs over finite fields. Des Codes Crypto, DOI 10.1007/s10623-014-9988-7 (2014).



Figure: The Duel: Timo Boll vs. KUKA Robot

Theorem (De Boeck, Nakić, 2015) If  $(\mathcal{V}, \mathcal{B})$  is a 3- $(v, k, \lambda)_q$  design with tactical decomposition

 $\mathcal{V} = \mathcal{V}_1 \sqcup \cdots \sqcup \mathcal{V}_m, \ \mathcal{B} = \mathcal{B}_1 \sqcup \cdots \sqcup_n,$ 

then

$$\begin{split} \sum_{j=1}^{n} \rho_{lj} \kappa_{rj} \kappa_{sj} &= \\ &= \begin{cases} \lambda_1 + & \Lambda_{lrs} \cdot \lambda_2 + & (|\mathcal{V}_r| \cdot |\mathcal{V}_s| - \Lambda_{lrs} - 1) \cdot \lambda_3, & \text{ for } l = r = s, \\ & \Lambda_{lrs} \cdot \lambda_2 + & (|\mathcal{V}_r| \cdot |\mathcal{V}_s| - \Lambda_{lrs}) \cdot \lambda_3, & \text{ otherwise.} \end{cases} \end{split}$$

 De Boeck, Nakić: Necessary conditions for the existence of 3-designs over finite fields with non-trivial automorphism groups.
 Finished! (2015).



Theorem (De Boeck, Nakić, 2015) If  $(\mathcal{V}, \mathcal{B})$  is a 3- $(v, k, \lambda)_q$  design with tactical decomposition

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 De Boeck, Nakić: Necessary conditions for the existence of 3-designs over finite fields with non-trivial automorphism groups.
 Finished! (2015).

# Open problem

Do Steiner systems  $3-(v, k, 1)_q$  exist?

# Some results regarding parameter $\Lambda_{lrs}$

1. 
$$\Lambda_{lrs} = \Lambda_{lsr}$$

2. 
$$|\mathcal{V}_l| \cdot \Lambda_{lrs} = |\mathcal{V}_r| \cdot \Lambda_{rls}$$

3. 
$$\sum_{s=1}^{m} \Lambda_{lrs} = \begin{cases} |\mathcal{V}_r| \cdot (q+1) + \frac{q^{\nu} - q^2}{q-1} - 1, & l = r, \\ |\mathcal{V}_r| \cdot (q+1), & l \neq r. \end{cases}$$



Figure: Bladerunner

## Lemma

The set of 2-subspaces of  $\mathbb{F}_q^v$  is a  $2 - (v, 2, 1)_q$  design  $(\mathcal{V}, \mathcal{L})$ . Group  $G \leq P\Gamma L(\mathbb{F}_q^v)$  acts on  $(\mathcal{V}, \mathcal{L})$  inducing tactical decomposition

$$\mathcal{V} = \mathcal{V}_1 \sqcup \cdots \sqcup \mathcal{V}_m, \qquad \mathcal{L} = \mathcal{L}_1 \sqcup \cdots \sqcup \mathcal{L}_\omega$$

with tactical decomposition matrices  $[\rho_{ij}^{\mathcal{L}}]$  and  $[\kappa_{ij}^{\mathcal{L}}]$ . Then

$$\Lambda_{lrs} = \begin{cases} \sum_{j=1}^{\omega} \rho_{lj}^{\mathcal{L}} \kappa_{rj}^{\mathcal{L}} \kappa_{sj}^{\mathcal{L}} - \lambda_{1}^{\mathcal{L}}, & \text{ for } l = r = s, \\ \sum_{j=1}^{\omega} \rho_{lj}^{\mathcal{L}} \kappa_{rj}^{\mathcal{L}} \kappa_{sj}^{\mathcal{L}}, & \text{ otherwise.} \end{cases}$$



# Thank you for your attention!



But they are useless. They can only give you answers. Pablo Picasso

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